

Rayat Shikshan Sanstha's Karmaveer Bhaurao Patil College of Engineering, Satara

Criterion 7 – Institutional Values and Best Practices Key Indicator - 7.2 Best Practices

7.2.1 Describe at least two institutional best practices.

Sr.No.	Documentary Evidences / Sample Documents	Page No.
1	Sample documents for project based Learning	1-70
2	Sample documents for Library book bank Scheme.	71-85

Project Based Learning

Year: 2018-19

Semester: VII

Subject: Remote Sensing & Application of GIS in Civil Engineering

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PROJECT BASED LEARNING

DEPARTMENT OF CIVIL ENGINEERING

COURSE: REMOTE SENSING & APPLICATION OF GIS IN CIVIL ENGINEERING

CLASS: B.E. (CIVIL)

SEMISTER: VII

YEAR: 2018-19

DURATION:

TITLE: TYPES OF RESOLUTIONS USED IN REMOTE SENSING

1. INTRODUCTION

In remote sensing the term resolution is used to represent the resolving power, which includes not only the capability to identify the presence of two objects, but also their properties. In qualitative terms the resolution is the amount of details that can be observed in an image. Four types of resolutions are defined for the remote sensing systems.

- Spatial resolution
- Spectral resolution
- Temporal resolution
- Radiometric resolution

2. SPATIAL RESOLUTION

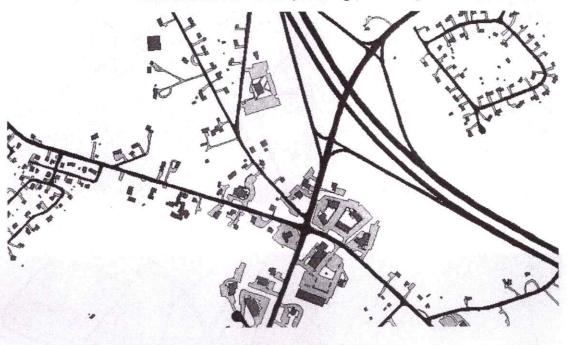
Spatial Resolution describes how much detail in a photographic image is visible to the human eye. The ability to "resolve," or separate, small details is one way of describing what we call spatial resolution. Spatial resolution of images acquired by satellite sensor systems is usually expressed in meters.

For example, we often speak of Landsat as having "30- meter" resolution, which means that two objects, thirty meters long or wide, sitting side by side,

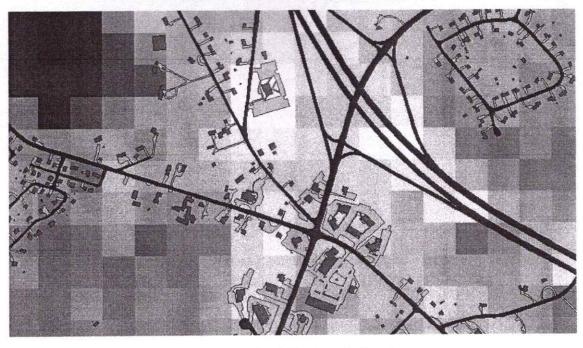
can be separated (resolved) on a Landsat image. Other sensors have lower or higher spatial resolutions.

Spatial Resolutions

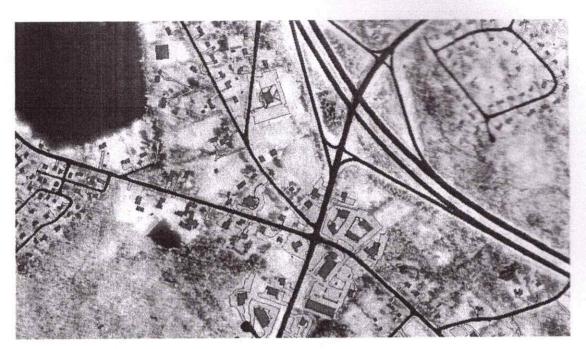
Planimetric Data - Roads, Buildings, Driveways



80 Meter MSS w/ Planimetric Overlay



1 Meter DOQ w/ Planimetric Overlay



Sub-meter Data w/ Planimetric Overlay



Spatial resolution usually refers to the size of the instantaneous field of view (IFOV) or the ground pixel. Although alternative definitions exist (Mather, 1987), this is the meaning that will be used here. The IFOV is the area on the ground that is viewed by the sensor at a given instant in time. As such, it usually represents the ground area that is represented by each pixel in a

remotely sensed image. The IFOV can be indicated as the ground dimensions of each pixel, or as the instantaneous angular measurement of the sensor field of view.

Spatial resolution is controlled by the scan rate, the dimensions of the detector array, and the rate at which the analog output, produced by each detector element as the scanning mirror sweeps across the surface, is integrated and sampled for conversion to digital output.

Spatial resolution is usually given as "nominal" spatial resolution which refers to the resolution for a sample obtained from the nadir viewing position at the specified altitude of the satellite.

For some sensors, the actual resolution can vary considerably across the scan line. This is especially problematic for the Advanced Very High Resolution Radiometer (AVHRR) sensors aboard the NOAA series of meteorological satellites.

Due to the wide swath width of the AVHRR instrument (+/- 56 degrees from the surface normal or about 3000 km) AVHRR pixel dimensions become increasingly distorted away from nadir as view zenith angles increase. At the extreme edges of the scan, the nominal AVHRR resolution of 1.1 km is distorted to 2.4 km in the along track direction, and 6.5 km in the across track direction (Goward *et al.* 1991).

Spatial resolution has important implications for:

- how we define objects on the surface;
- · the scale of analysis;
- locational precision and accuracy;

- areal accuracy;
- purity of the spectral response;
- data volume and data processing costs.

The higher (or finer) the *spatial resolution*, the more completely and precisely the *shapes* of objects are sampled, the more readily objects can be identified based on their shape, and the more accurately the precise location, extent and area of objects can be determined.

As such, the spatial resolution of the data must be able to support the objectives of a given remote sensing project. Clearly, mapping the boundaries of the reservoir shown in Figure 14 cannot be adequately achieved using 1 km resolution data.

Frequently, an important consideration in sensor design is balancing the objectives of attaining high spatial resolution, while maintaining a high signal/noise ratio. The smaller the IFOV, the less total radiant energy will be incident upon the detector element. As a result, the signal/noise ratio will suffer. This can be counterbalanced by either increasing the dwell time, or increasing the spectral bandwidth.

2. SPECTRAL RESOLUTION

Spectral resolution refers to the number, spacing, and width of the sampled wavelength bands along the electromagnetic spectrum. Technically, spectral resolution is controlled by the beam splitting and focusing apparatus in the sensor, by the design of the detector arrays, and by the specific sensitivities of the photon detectors, or photovoltaic elements in the detector arrays.

It is known and easily observable that different surface objects have unique, or characteristic spectral signatures.

The higher the *spectral resolution*, the more completely and precisely the *spectral signature* of each individual IFOV will be sampled, and the more readily different scene elements can be classified or discriminated based on those signatures. The following figure shows how a common sensor, Landsat Thematic Mapper, samples the spectra of three common scene elements.

Spectral band width and band placement are typically chosen so as to:

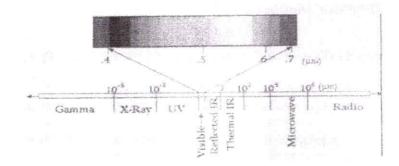
- take advantage of (sample) key unique characteristics of the spectral signatures for the different surface elements of particular interest;
- avoid atmospheric absorption bands, or wavelength regions within
 which the atmosphere is most prone to absorb the incident and surface
 surface-leaving radiant flux as it propagates toward (radiance) and away
 from (irradiance) the surface.

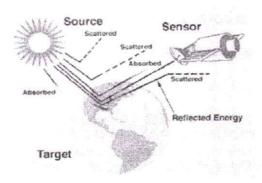
The dramatic differential between red (0.63 to 0.69 um on TM) and near-infrared (0.76 to 0.90 um) reflectance seen in Figure 5 is a well recognized spectral feature for vegetation. Most sensors sample in these two wavelength bands. For an example, go back to red edge. "Vegetation Indices" are designed to capitalize on the information contained in reflectance measurements made in these portions of the electromagnetic spectrum to indicate the abundance or physiological characteristics of the vegetation on the surface.

An important consideration in sensor design is balancing the objectives of keeping the sampled spectral bands narrow, while maintaining a high signal/noise ratio. The narrower the wavelength band, the less total radiant

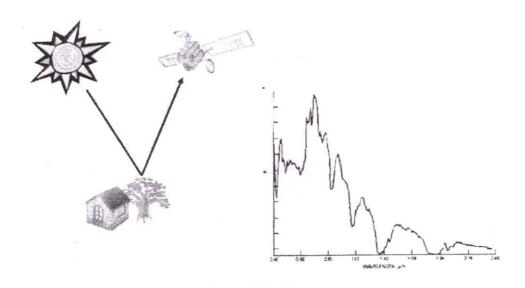
energy will be incident upon the detector element. This is because a smaller "slice" of the total radiant flux is being sampled. As a result, the strength of the signal will be reduced relative to the magnitude of the background noise of the sensor. In order to maintain high image quality, the signal/noise ratio must be kept large.

Electromagnetic Radiation (EMR)





- Number of spectral bands (red, green, blue, NIR, Mid-IR, thermal, etc.)
- Width of each band
- Certain spectral bands (or combinations) are good for identifying specific ground features
- Panchromatic 1 band (B&W)
- Color 3 bands (RGB)
- Multispectral 4+ bands (e.g. RGBNIR)
- Hyperspectral hundreds of bands



Spectral Response Curve

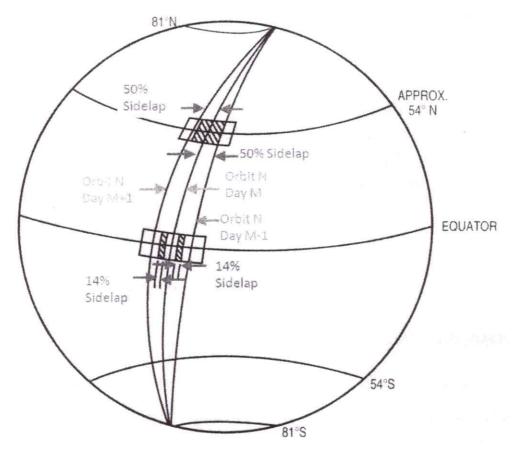
3. TEMPORAL RESOLUTION

Temporal resolution describes the number of times an object is sampled or how often data are obtained for the same area. The absolute temporal resolution of a remote sensing system to image the same area at the same viewing angle a second time is equal to the **repeat cycle** of a satellite.

The repeat cycle of a near polar orbiting satellite is usually several days, eg., for IRS-1C and Resourcesat-2 it is 24 days, and for Landsat it is 18 days. However due to the off-nadir viewing capabilities of the sensors and the sidelap of the satellite swaths in the adjacent orbits the actual revisit period is in general less than the repeat cycle.

The actual temporal resolution of a sensor therefore depends on a variety of factors, including the satellite/sensor capabilities, the swath overlap, and latitude. Because of some degree of overlap in the imaging swaths of the adjacent orbits, more frequent imaging of some of the areas is possible. Fig

shows the schematic of the image swath sidelap in a typical near polar orbital satellite.



Sidelap In A Typical Near Polar Satellite Orbit

From Fig.3it can be seen that the sidelap increases with latitude. Towards the polar region, satellite orbits come closer to each other compared to the equatorial regions. Therefore for the polar region the sidelap is more.

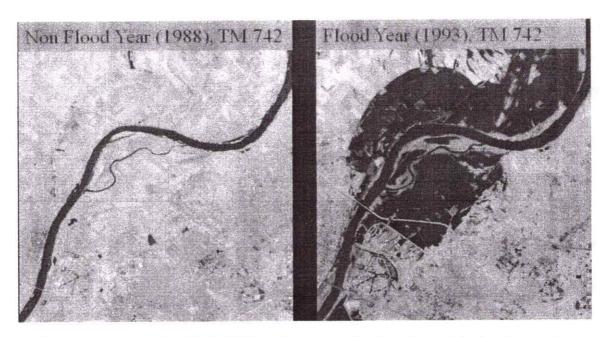
Therefore more frequent images are available for the polar region. In addition to the sidelap, more frequent imaging of any particular area of interest is achieved in some of the satellites by pointing their sensors to image the area of interest between different satellite passes. This is referred as the off-nadir viewing capability.

For example: using pointable optics, sampling frequency as high as once in 1-3 days are achieved for IKONOS, whereas the repeat cycle of the satellite is 14 days.

Images of the same area of the Earth's surface at different periods of time show the variation in the spectral characteristics of different features or areas over time. Such multi-temporal data is essential for the following studies.

- Land use/land cove classification
- Temporal variation in land use / land cover
- · Monitoring of a dynamic event like
- Cyclone
- Flood
- Volcano
- Earthquake

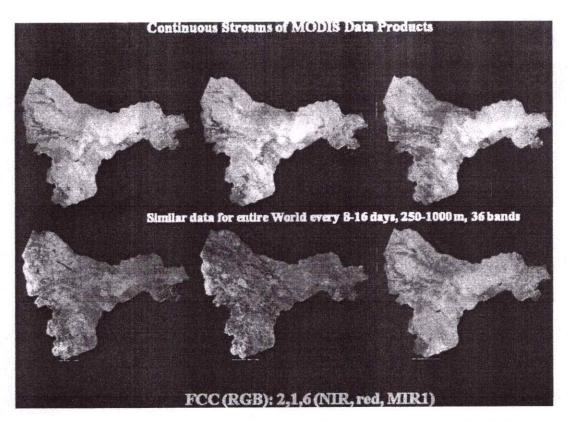
Flood studies: Satellite images before and after the flood event help to identify the aerial extent of the flood during the progress and recession of a flood event. The Great Flood of 1993 or otherwise known as the Great Mississippi and Missouri Rivers Flood of 1993, occurred from April and October 1993 along the Mississippi and Missouri rivers and their tributaries. The flood was devastating affecting around \$15 billion and was one of the worst such disasters occurring in United States. Fig. shows the landsat TM images taken during a normal period and during the great flood of 1993. Comparison of the two images helps to identify the inundated areas during the flood.



Landsat TM images of the Mississipi River during non-flood period and during the great flood of 1993

Land use/ land cover classification: Temporal variation in the spectral signature is valuable in land use/ land cover classification. Comparing multi-temporal images, the presence of features over time can be identified, and this is widely adopted for classifying various types of crops / vegetation. For example, during the growing season, the vegetation characteristics change continuously. Using multi-temporal images it is possible to monitor such changes and thus the crop duration and crop growth stage can be identified, which can be used to classify the crop types viz., perennial crops, long or short duration crops.

Fig. 6 shows the MODIS data product for the Krishna River Basin in different months in 2001. Images of different months of the year help to differentiate the forest areas, perennial crops and short duration crops.



False Color Composites (FCC) of the Krishna River Basin generated from the MODIS data for different months in 2001.

4. RADIOMETRIC RESOLUTION

Radiometric resolution of a sensor is a measure of how many grey levels are measured between pure black (no reflectance) to pure white. In other words, radiometric resolution represents the sensitivity of the sensor to the magnitude of the electromagnetic energy. The finer the radiometric resolution of a sensor the more sensitive it is to detecting small differences in reflected or emitted energy or in other words the system can measure more number of grey levels. Radiometric resolution is measured in bits.

Each bit records an exponent of power 2 (e.g. 1 bit = 21 = 2). The maximum number of brightness levels available depends on the number of bits used in representing the recorded energy. For example, shows the radiometric resolution and the corresponding brightness levels available.

Radiometric resolution	Number of levels	Example
1 bit	2 ¹ – 2 levels	
7 bit	2 ⁷ – 128 levels	IRS 1A & 1B
8 bit	2 ⁸ – 256 levels	Landsat TM
11 bit	2 ¹¹ – 2048 levels	NOAA-AVHRR

Radiometric Resolution and the Corresponding Brightness Levels

Thus, if a sensor used 11 bits to record the data, there would be 211=2048

digital values available, ranging from 0 to 2047. However, if only 8 bits were

used, then only 28=256 values ranging from 0 to 255 would be available. Thus,
the radiometric resolution would be much less. Image data are generally

displayed in a range of grey tones, with black representing a digital number of
0 and white representing the maximum value (for example, 255 in 8-bit data).

By comparing a 2-bit image with an 8-bit image, we can see that there is a
large difference in the level of detail discernible depending on their
radiometric resolutions. In an 8 bit system, black is measured as 0 and white is
measured as 255. The variation between black to white is scaled into 256
classes ranging from 0 to 255. Similarly, 2048 levels are used in an 11 bit
system as shown in Fig.

Finer the radiometric resolution, more the number of grey levels that the system can record and hence more details can be captured in the image.

Fig. shows the comparison of a 2-bit image (coarse resolution) with an 8-bit image (fine resolution), from which a large difference in the level of details is apparent depending on their radiometric resolutions.

As radiometric resolution increases, the degree of details and precision available will also increase. However, increased radiometric resolution may increase the data storage requirements.

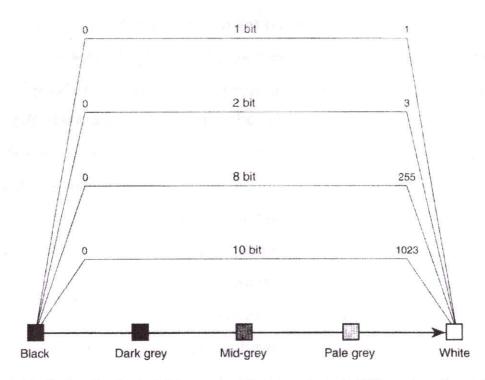


Fig 1 Variation in the brightness levels recorded at different radiometric resolution

2Bit Data (Coarse)

8Bit Data (Fine)





Fig.2 Comparison of a coarse resolution 2-bit image with a fine resolution 8-bit image

In an image, the energy received is recoded and represented using Digital Number (DN). The DN in an image may vary from 0 to a maximum value, depending up on the number of gray levels that the system can identify i.e., the radiometric resolution. Thus, in addition to the energy received, the DN for any pixel varies with the radiometric resolution. For the same amount of energy received, in a coarse resolution image (that can record less number of energy level) a lower value is assigned to the pixel compared to a fine resolution image (that can record more number of energy level). This is explained with the help of an example below.

Example: A RS system with a radiometric resolution of 6 bits assigns a DN of 28, 45 and 48 to three surfaces. What would be the equivalent DNs for the same surfaces if the measurements were taken with a 3 bit system?

The DNs recorded by the 3-bit system range from 0 to 7 and this range is equivalent to 0-63 for the 6 bit system.

012 34567 (3 bit)

0 9 18 27 36 45 54 63 (6 bit)

Therefore a DN of 28 on the 6-bit system will be recorded as 3 in the 3-bit system. A 6-bit system could record the difference in the energy at levels 45 and 47, whereas in a 3-bit system both will be recorded as 5.

Therefore when two images are to be compared, they must be of same radiometric resolution.

REFERENCES:

- 1. https://www.unc.edu/~aaronm/RSCC/
- 2.<u>www.edc.uri.edu/nrs/classes/NRS409/RS/Lectures/HowRemoteSensonWork.</u>
 pdf
- 3. https://nptel.ac.in/courses/105108077/module2/lecture8.pdf

BIBLIOGRAPHY:

1. Gibson P.J (2000) "Introductory Remote Sensing- Principles and Concepts" Routledge, London.



Rayat Shikshan Sanstha's

Karmaveer Bhaurao Patil College of Engineering, Satara

Academic Year: 2018-19 Name of course: STQA

Class: BE

Semester-II Course Code:

Project Based Learning List

Sr.No.	Group ID	Members of the Group	Title of the project	Sign
1	G1	Mayuri Rajebhosale	Jot based	ZI)
2		Sayali phanase	home	Galin
3	1 -	Chaitrali Kulkarni	antomateur	Phon
4	V	Tejas Kurle	2 Chiston	Ti
5	G2	Priyanka Duduskar.	Tracking and	Dinantes.
6		Shraddha Gaikwad.		721
7		Swapnali kachare.	- billing applical	siskachare
8		Shubhangi khude.	related to cyber seconity devices	dayde
9	G3	Shrutika Suresh Oswal	Fip System For	Csualis
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11	PURSE NOTES	Ankita Satyawan Gaikwad	- Akashganga pullin	(Docikerael
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Course Coordinator Mr. Vikas Chavan Head of the Department Dr. Shabina Sayyed



Karmaveer Bhaurao Patil College of Engineering, Satara

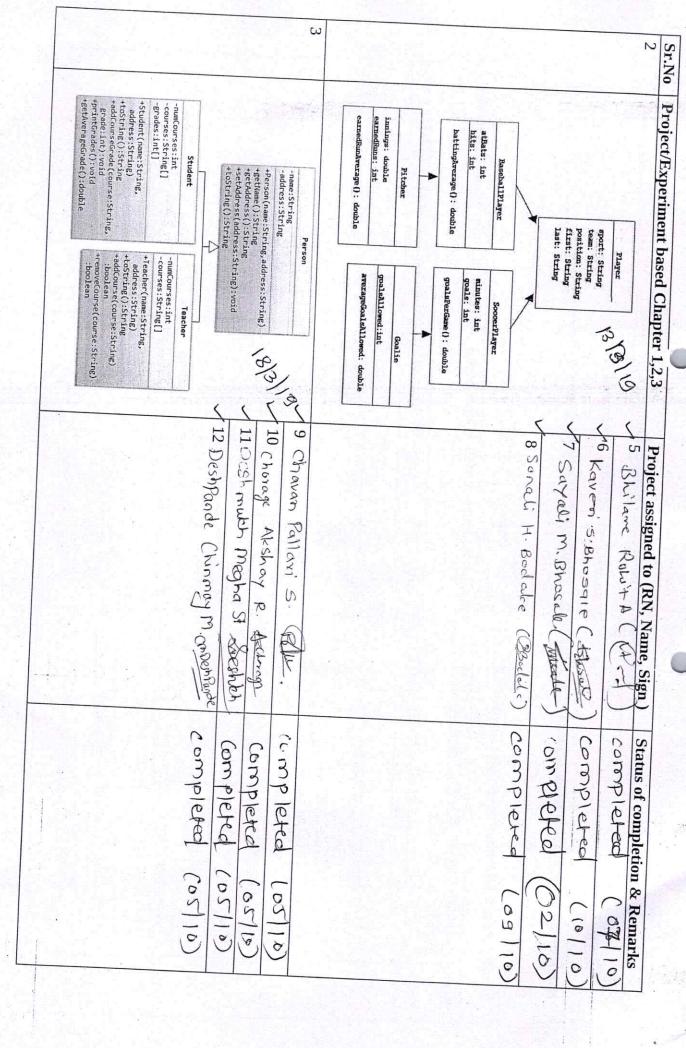
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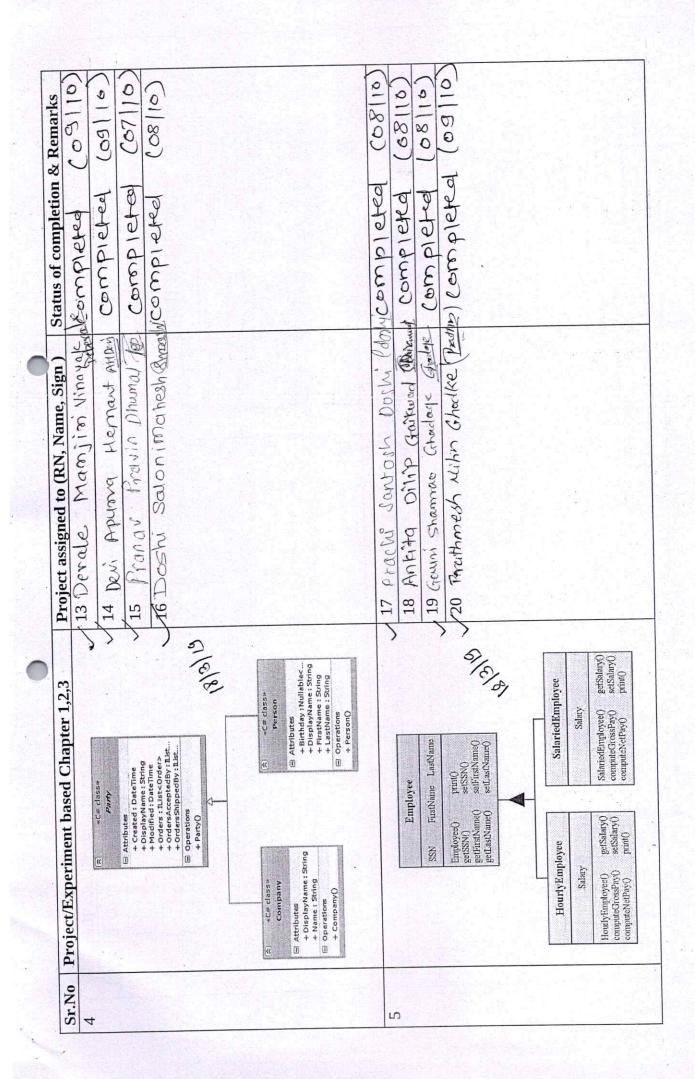
Name of the Course: Programming Laboratory IV

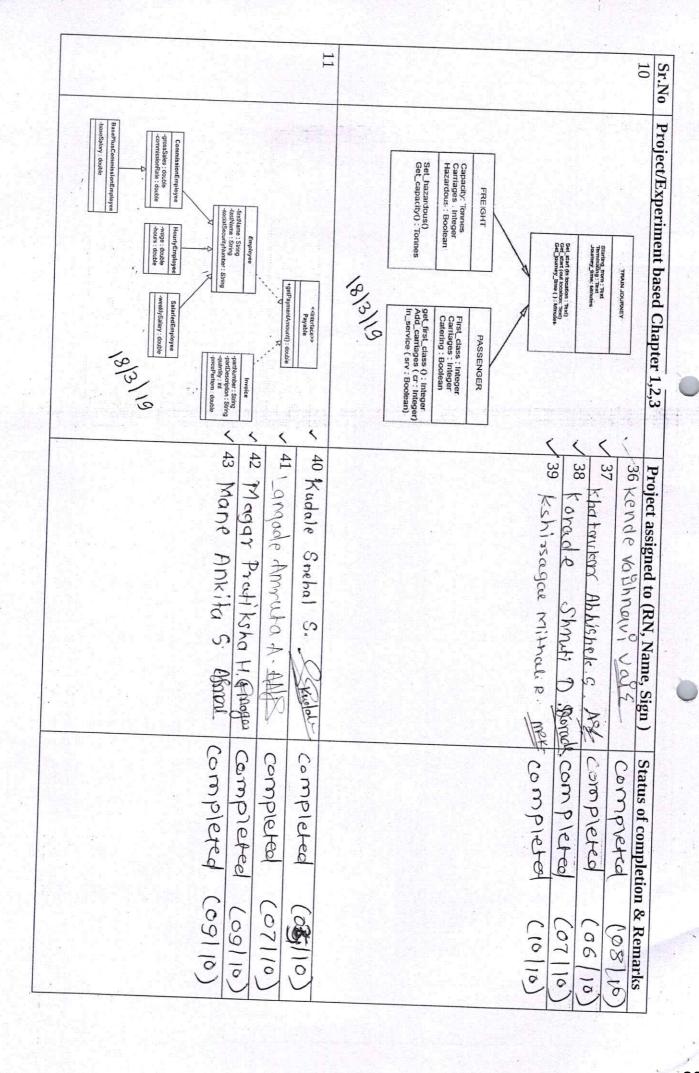
Name of the Program: Computer Science and Engineering Name of the course Coordinator: Prof. Rasal S. A.

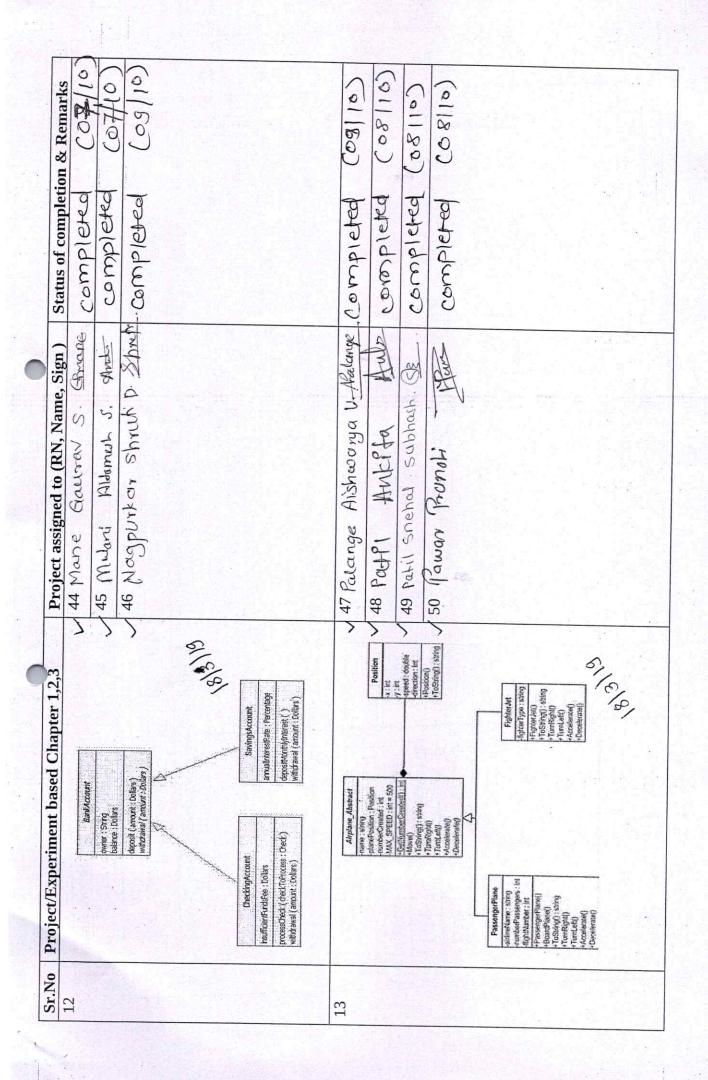
Project Based Learning based on Chapter 1,2,3,4,5

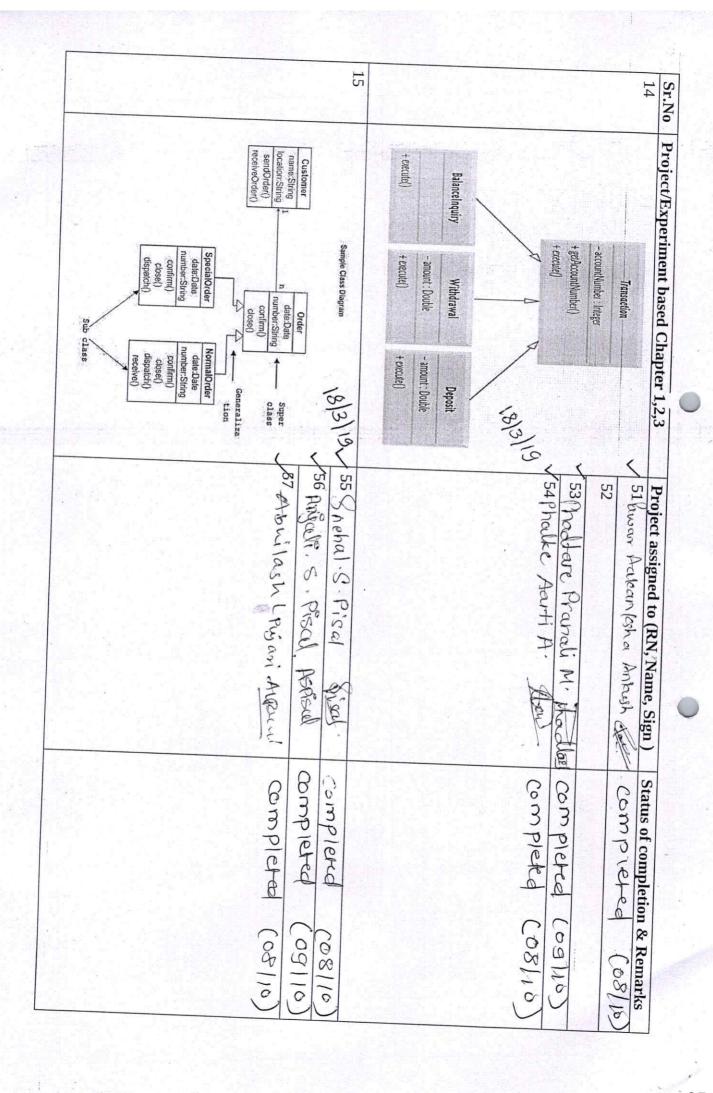
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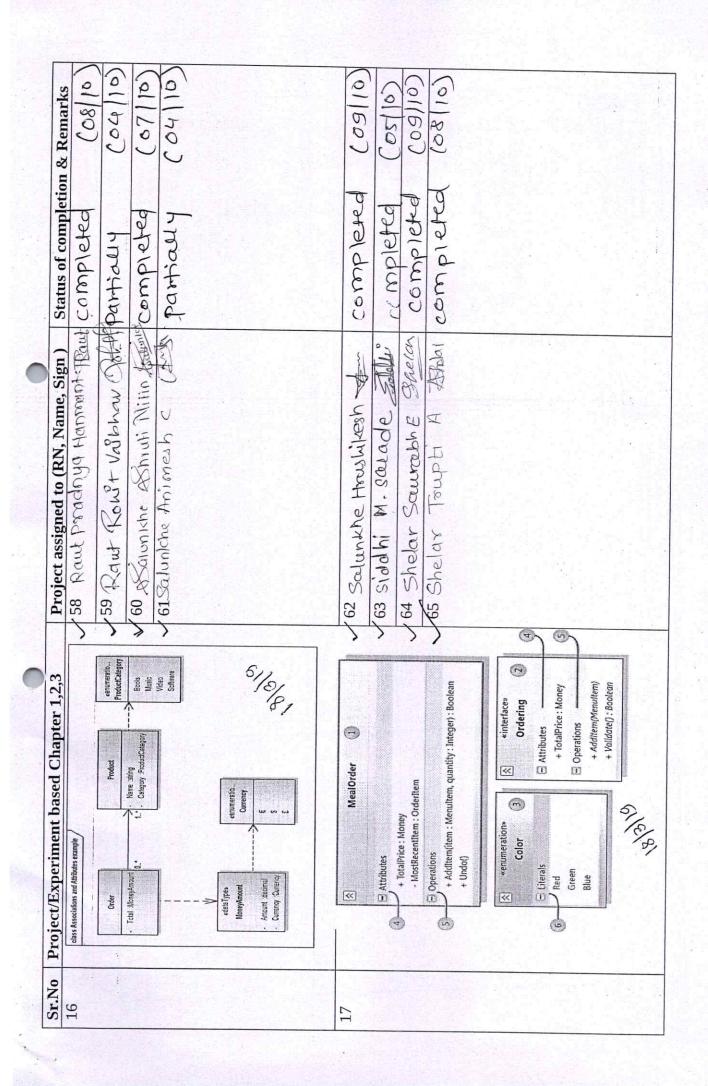


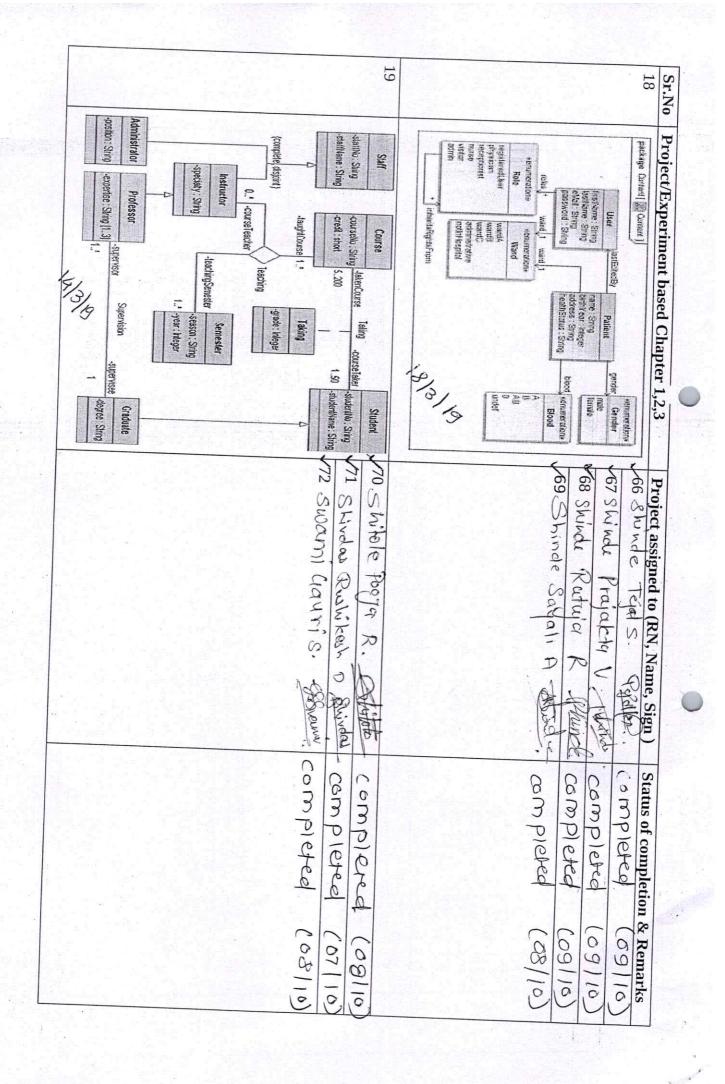


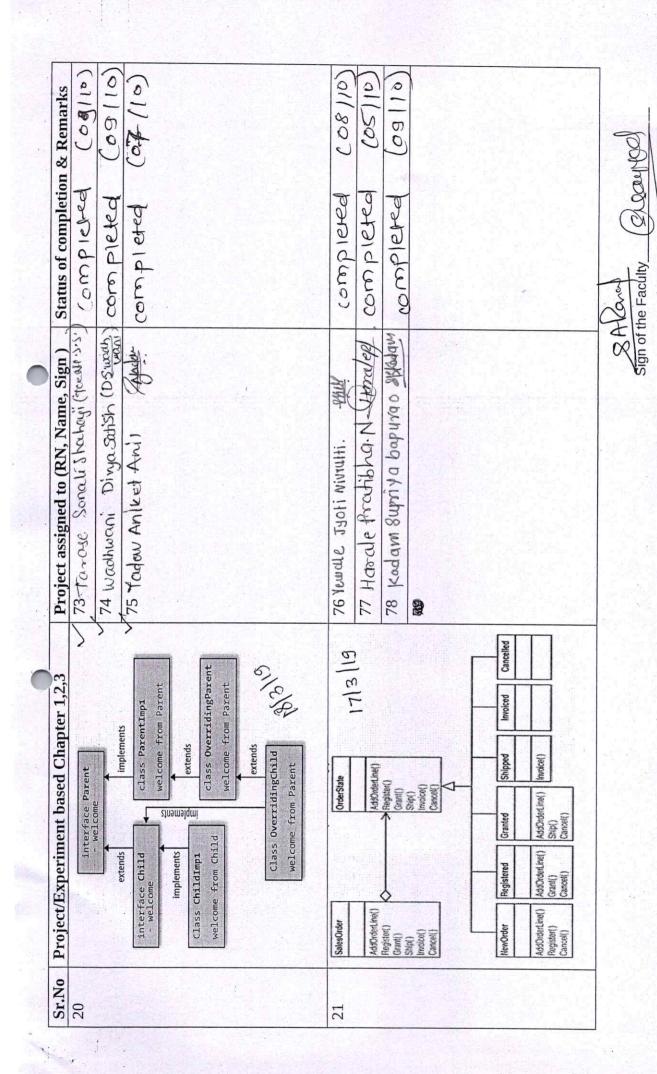












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Date:- 13/04/2018

Submitted,

Subject: - About permission to organize one month certificate course on Project Based Learning for B.E. Electronics class.

Sir,

With reference to above subject, the Electronics Department is organizing one month certificate course on "Project Based Learning" for B.E. Electronics class, from 6/06/2018 to 24/6/2018

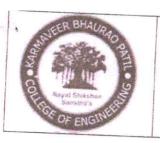
Please give the permission to conduct the certificate course.

Electronics Engineering Department.

To, Principal, Karmaveer Bhaurao Patil

College of Engineering, Satara.





Rayat Shikshan Sanshta's

Karmaveer Bhaurao Patil College of Engineering, Satara Department of Electronics Engineering

Office order:

Date: 04/06/18

All the Staff Members of the Department are hereby informed to follow the schedule and attend **regularly** the Sessions of Certificate Course in "Project Based Learning" as per given below.

Sr. no	Date	
1		Name of Staff
2	5 th – 9 th June 2018	Mr. Jagdale S. J. & Mr. Bhosale S. S.
2.	11 th -16 Th June 2018	Mr. Nale P. M. & Mr. Pharande R. M.
3.	18 th – 24 th June 2018	Mr. Jagdale S. J. & Mr. Bhosale S. S.
	70 24 Julie 2018	Mr. Nale P. M. & Mr. Pharande R. M.

Co-ordinator

Head



Rayat Shikshan Sanstha's Karmaveer Bhaurao Patil College of Engineering, Satara

Department of Electronics Engineering Certificate Course in Project Based Learning For Electronics Engineering Course Timing:- 10.00 a.m. to 6.00 p.m.

Date	Tir	ne			Topic to be covered	Faculty
	From	To	Hours			
	10:30 AM	11.00 AM	1		Inaguration	
0.499.00	11.00 AM		2			Deef D.I. Deud
		3.00 PM	2	Theory	What is project, Theme, How to develop, Theories and practices Introduction of Electronics: Voltage, Current, Resistance, Capacitance, Inductance, KCL, KVL, Voltage and current devision laws, Superposition Theorem, Thevenins Theorem, Nodal And Mesh analysis, voltage source to current source and current source to voltage source conversion.	Prof. R.J. Devi Prof. R.J. Devi
				Hands On	Tools required and how to use: Multimeter, Solder Gun, Screw Driver Set, Tester, Breadboard; Connecting Wires/Connectors, General purpose PCB.	Prof. R.J. Devi
	3.00 PM	5.30 PM	2	Hands On	Instruments handling study: Power Supply, Signal Generator, CRO/DSO, DMM, Spectrum Analyzer, choosing an appropriate measuring instrument / tool	Prof. R.J. Devi
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e alda,	10:30 AM	12.30 AM	2	Hands On	Resistor,Capacitor & Inductor: How a it works,Units,different Types, How to recognize and select it	Dr. Aldar D.S.
07-Jun-16	1.30 PM	3.00 PM	Ž	Hands On	Different circuit implementations using Resistor, Capacitor & Inductor, Applications of Resistor capacitor & inductor	Dr. Aldar D.S.
	3.30 PM	5.30 PM		Hands On	understanding by implementing KCL, KVL, oltage and current devision laws, Theorems	Dr. Aldar D.S.
08-Jun-16	10:30 AM	12.30 AM	- 2	Hands On	Current limiting techniques: undestanding, compnetnts used for current limiter, implementation of current limiter cuircuts, roles of resister,capacitor and resistor in current limiting.	Dr. Aldar D.S.
08-Jun-16	1.30 PM	3.00 PM	2	Hands On	Indtroduction of LEDs: single color, two color, RGB Color	Dr. Aldar D.S.
	3.30 PM	5.30 PM	2		Design calculations and implementation of LED lights using single color, single LED light, LED Array lights	Dr. Aldar D.S.
09-Jun-16					Design calculations and implementation of LED lights using two color and RGB	Dr. Aldar D.S.
	10:30 AM	12.30 AM	2	Theory	Diode: understastanding construction and working, different types of diode: Zener, Tunnel Diode, Varactor Diode, Shockley Diode, Photo-diode,PIN diode, applications of diodes: switch, clipper,clamper,voltage multiplier & doubler,Rectifier; Slection of appropriate diode	Dr. Aldar D.S.
	1.30 PM	3.00 PM	2	Hands On	Working with diode: testing diodes, designing different circuits of diode, developing Gates Using diode,	Dr. Aldar D.S.
	3.30 PM	5.30 PM	2	Hands On	Developing and testing of different circuits using zener, photo diode, PIN diode.	Dr. Aldar D.S.
	10:30 AM	12.30 AM	2	Theory	Transistor: under standing working, characteristics and different circutal combination of transister such as switch, amplifier, current limiter, multivibrator, oscillator, testing of transistors	Dr. Aldar D.S.
10-Jun-16	1.30 PM	3.00 PM	2	Hands On	NPN and PNP transister circuits design and testing such as switch amplifiers, Bulding audio amplifier with transisters	Dr. Aldar D.S.
	3.30 PM	5.30 PM	2	Hands On	transister circuits design and testing such as current limiter and Oscillators	Dr. Aldar D.S.
	10:30 AM	12.30 AM	2	Theory	FET and MOSFET: under standing working, characteristics and different circutal combination, testing of FET, MOSFET	
11-Jun-16	1.30 PM	3.00 PM	2	Hands On	amplifiers	
	3.30 PM	5.30 PM	2	Hands On	P channel and N channel MOSFET Circuits design and testing: amplifiers and oscillators	Dr. Aldar D.S.
	10.00	12.20	-	The	Transformer Bolov actuation contractors CCD	Mr.Mane S.S.
	-	12.30 AM	2	Theory	Transformer, Relay, actuators , contactors, SSR	
13-Jun-16	1.30 PM	3.00 PM	2	Hands On Hands On	designing and testing circuits using IC 74HC4017 Decade counter, mux,	Prof. R.J. Devi
1 3 5 5 6	3.30 PM 10:30 AM	5.30 PM 12.30 AM	2	Theory	demux, encoder, decoder IC, optoisolator Timer 555: introduction, working and different application design	Prof. R.J. Devi
14-Jun-16		3.00 PM	2	Hands On	가 하는 보고 하는 이 경소에 가는 가게 하는 무슨 사람이 있는 것이 없는 것들이 되었습니다. 그런 보고 하는 것이 없는 것이 없는 것이다. 그런 사람이 되었습니다. 그런 것이 없는 것이 없는 것이 사람들이 없는 것이다. 그런 것이 없는 것이 없는 것이다. 그런 것이 없는 것이 없는 것이다. 그런 것이다.	Mrs.Thorat R.A
	3.30 PM	5.30 PM	2	Hands On	Bt138 /bt139/bt151 ,DIAC/SDIAC, Thyristor (SCR or TRIAC): Nxp Bt152-600R 13A or 2N6342A with moc3021, , Thyristor applications	Mrs.Thorat R.A

	10:30 AM	12.30 AM	2		WOST ET THE THOUGHT I THE THOUGHT OF THE THOUGHT.	Mrs.Thorat R.A.
5-Jun-16	L.30 PM	3.00 PM	2	Hands On	using thyristers, mosfets, IGBTs. Switches: Different types of Switches, CMOS Analog Switche, key pads and interfacing	Dr. Aldar D.S.
	HWITE E		2	Hands On	Interfacing of Motor and other electric, pneumatic and hydraulic	Prof. R.J. Devi
		5.30 PM			actuating devices	D. Alder D.C.
6-Jun-16	10:30 AM	12.30 AM	2		OPAMPs: overview, different circuits design using opamps	Dr. Aldar D.S.
	1.30 PM	3.00 PM	2		OPAMPs: study of LM741, LM358,LM324,TL072,TL082 and other available OPA2604 and OPA2134	Dr. Aldar D.S.
	3.30 PM	5.30 PM	2	Hands On	Single supply opamp design and dual supply opamp design, Analogue comparator, audio amplifier, V to I, I to V	Dr. Aldar D.S.
		12.30 AM	2	Hands On	Signal Conditioning Design and testing , designing of 4-20 ma Current	Dr. Aldar D.S.
7-Jun-16	1 20 064	3.00 PM	2	Hands On	Source filters and Oscillators design using opamp	Dr. Aldar D.S.
7-3011-10	1.50 PWI	3.00 FIVE		Hands On	Circuit Design: Current, Power Calculation, Heat Sink and Designing a	Prof. R.J. Devi
	3.30 PM	5.30 PM	2		power supply	D- Alder D.S
	10:30 AM	12.30 AM	2		Drawing a circuit schematic and Circuit simulation, parameters setting	Dr. Aldar D.S.
18-Jun-16	1.30 PM	3.00 PM	2	Hands On	TINA: circuit simulation using TINA and building the circuit on breadboard and testing of it.	Dr. Aldar D.S.
	3.30 PM	5.30 PM	2	Hands On	ORCAD: Circuit simulation using ORCAD and building the circuit on breadboard and testing of it.	Mr.Bhandare N.D.
	10-30 AM	12.30 AM	2	Theory	MULTISIM: Circuit simulations and building the circuit on breadboard	Mr.Bhandare N.D.
				Hands On	and testing of it. Proteus: circuit simulationsnd building the circuit on breadboard and	Mr.Bhandare N.D.
20-Jun-16	1.30 PM	3.00 PM	2	Hands On	testing of it. PCB Design Process: Layouts, study of aesthetics and convenience,	Mr.Bhandare N.D.
26-46		5.30 PM		Hands On	Enclosures Implementation of schematics, layout and prining using DIPTrace and	Mr.Bhandare N.D.
21-Jun-16	10:30 AM	12.30 AM	2		itching and soldering the components Implementation of schematics, layout and prining using DIPTrace and	Mr.Bhandare N.D.
	1.30 PM	3.00 PM	2		itching and soldering the components	STATE OF THE PARTY.
	3.30 PM	5.30 PM	2	Hands On	implementation of schematics, layout and prining using Eagle and itching and soldering the components	Mr.Bhandare N.D.
	10:30 AM	12.30 AM	2	Hands On	implementation of schematics, layout and prining using Eagle and itching and soldering the components	Mr.Bhandare N.D.
22-Jun-16	1.30 PM	3.00 PM	2	Hands On	Regulator: Different Regulator Ics, 78XX/79XX/LM317 and applications ,TVS: TVS Diode Selection Guide(AND8230), LDO: LP2985 and applications, SMPS LM3524D,	Prof. R.J. Devi
	3.30 PM	5.30 PM	2	Hands On	Powe supply design and testing	Dr. Aldar D.S.
		12.30 AM	2		Circuit design and testing using TI Webench	Dr. Aldar D.S.
23-Jun-16		3.00 PM	2	Hands On		Dr. Aldar D.S.
	3.30 PM	5.30 PM	2	Hands On		Dr. Aldar D.S.
	10:30 AN	12.30 AM	2	Thoery	Different types of DC motor and Controlling of DC motors,	Mr.Mane S.S.
24-Jun-16	1.30 PM	3.00 PM	2	Hands On	Stepper Motors: Different type of Stepper motors and Working with Stepper motors, Survo Motors: : Different survo motors	Mr.Mane S.S.
	3.30 PM	5.30 PM	2	Thoery	Different AC Motors	Mr.Mane S.S.
		1 12.30 AM	2		Embedded C insight	Prof. R.J. Devi
25-Jun-16	-		2		Microcontrollers:8051,ATMEGA328,ATMEGA16,PIC16/18/DSPIC	Prof. R.J. Devi
	3.30 PM	-	2	_	ARMLPC2148/ARM2368,MSP430,TIVA C, Arduino,	Prof. R.J. Devi
		12.30 AM	2		Raspberry Pi, BeagleBone, ATTINY, PICAXE	Prof. R.J. Devi
	1.30 PM	3.00 PM	2	-	RTC DS1307	Prof. R.J. Devi
26-Jun-16	3.30 PM	5.30 PM	2	Hands On	 	Prof. R.J. Devi
		12.30 AM	2	Hands On	Software design	Prof. R.J. Devi
	10.30 AN	I IZ.JU AIVI	4.00	Hands On		Prof. R.J.
27-Jun-16	1.30 PM	3.00 PM	2	Inalius Oil	Arduino, Mentor Graphic toolchain	Devi/Mr.Bhandar N.D.
	3.30 PM	5.30 PM	2	Hands On	ADC with example chips:	Prof. R.J. Devi
		12.30 AM	2		ADS1115 16-Bit ADC, ADS1220 24-bit.	Prof. R.J. Devi
	1.30 PM	3.00 PM	2	_	DAC MAP4925/MCP4921	Prof. R.J. Devi
28-Jun-16		STANCE STANCE	2		Wired and wireless communication: Bluetooth, Zigbee, RF transmitter receiver, Wifi, Capsense, Ethernet, GSM, GPS, Infrared, RFID,	Prof. R.J. Devi
	3.30 PM		1	Har da C	ultrasonic, I2C, SPI, UART, I2S, CAN, USB, DMA,	Dr. Aldar D.S.
		3.00 PM	2	Hands Or	Internet Of Things (IOT) : ThingSpeak, Temboo, IBM bluemix Android App development for Bluetooth and WiFI	Ut. Aluai U.S.
	1.30 PM			THERMORE CAP		

29-Jun-16	2 20 014	5.30 PM	2	Hands On	Antenna Design: HFSS/CST Studio/IE3D	Expert from othe institute
	3.30 PM	5.30 PM		Hands On	Same Design Examples, case study understanding stages of project	Prof. R.J. Devi
	5.30 PM	6.30 PM	1	Trialius Oil	work	
30-Jun-16	10:30 AM	12.30 AM	2	Thoery	Study of system requirements, Devising specifications, Reviewing other systems (Reviewing papers) Preparing a block schematic, inter block specifications, Devising a circuit, Design, Schematic, simulation, results, PCB, Circuit fabrication, cold and hot testing, Software development, commissioning of project.	Prof. R.J. Devi
	1.30 PM	3.00 PM	2	Hands On	Preparing Project synopsis format, Planning and scheduling the project, Project report format	Prof. R.J. Devi
	3.30 PM	5.30 PM	2		Objective test of 100 marks Valedictory	
	To	otal			138	1

Coordinator Dr. Sangle S.M.

Electronics Engg. Department

	10	Rayat Shikshan Sanstha's Karmaveer Bhaurao Patil College of Engineering, Sata	ra						
H A	监判	Department of Electronics Engineering	114						
N -		Certificate Course in Project Based Learning For Electronics Engineering							
G OF		Course Timing: 10.00 a.m. to 6.00 p.m.	ngmeering						
Date Th./Pr		Topic to be covered	Duration	Resource					
5,500.00	-	Inauguration at 9.30 a.m.	(In hrs.)	Person					
	-	What is project, Importance of project for building future, Theme, problem identification, How to							
5-Jun-18	Theory	develop, Theories and practices, Selection of Project, Literature survey and its importance, Steps in execution, Project Planning and work schedule, Synopsys format and writing, Daily Log Book, Monthly presentation and progress report, Seminar project I, Project report format and writing,	3	Prof. R.J. Devi,					
		Introduction of Electronics: Voltage, Current, Resistance, Capacitance, Inductance, KCL, KVL, Voltage and current devision laws, Superposition Theorem, Theorem, Nodal And Mesh analysis, voltage source to current source and current source to voltage source conversion.	4	Prof. R.J. Devi					
6-Jun-18	Hands On	Tools required and how to use: Multimeter, Solder Gun, Screw Driver Set, Tester, Breadboard, Connecting Wires/Connectors, General purpose PCB,	3	Mane S S					
	Hands On	Instruments handling study: Power Supply, Signal Generator, CRO/DSO, DMM, Spectrum Analyzer, choosing an appropriate measuring instrument / tool	3	Nanaware J D					
	Hands On	Resistor, Capacitor & Inductor: How a it works, Units, different Types, How to recognize and	-						
7-Jun-18		select it.Different circuit implementations using Resistor, Capacitor & Inductor, Applications of Resistor capacitor & inductor,	4	Dr. Aldar D S					
	Hands On	understanding by implementing KCL, KVL, voltage and current devision laws, Theorems	2	Dr. Aldar D S					
8-Jun-18	Hands On	Current limiting techniques: undestanding, compnetnts used for current limiter, implementation	6	Dr. Aldar D S					
	Hands On	of current limiter cuircuts, roles of resister capacitor and resistor in current limiting. Indtroduction of LEDs: single color, two color, RGB Color, Design calculations and	-	-1. 1 Hull 17 0					
9-Jun-18	Tidikas Off	implementation of LED lights using single color, single LED light, LED Array lights, Design calculations and implementation of LED lights using two color and RGB	6	Dr. Aldar D S					
11-Jun-18	Theory	Diode: understastanding construction and working, different types of diode: Zener, Tunnel Diode, Varactor Diode, Shockley Diode, Photo-diode, PIN diode, applications of diodes: switch, clipper, clamper, voltage multiplier & doubler, Rectifier; Slection of appropriate diode	3	Mrs. Mane S V					
11-Jun-10	Hands On	Working with diode: testing diodes, designing different circuits of diode, developing Gates Using							
		diode, Developing and testing of different circuits using zener, photo diode.	3	Mrs. Mane S V					
12-Jun-18	Theory	Transistor: under standing working, characteristics and different circutal combination of transister such as switch, amplifier, current limiter, multivibrator, oscilator, testing of transistors	3	Mrs. Mane S V					
	Hands On	NPN and PNP transister circuits design and testing such as switch amplifiers, Bulding audio amplifier with transisters, transister circuits design and testing such as current limiter and Oscillators	3	Mrs. Mane S V					
13-Jun-18	Hands On	FET and MOSFET: under standing working, characteristics and different circutal combination, testing of FET, MOSFET, P channel and N channel MOSFET Circuits design and testing: switch and amplifiers, P channel and N channel MOSFET Circuits design and testing: amplifiers and	4	Mrs. Mane S V					
	Theory	oscillators. Transformer, Relay, actuators, contactors, SSR	3	Mane S S					
	Hands On	Timer 555: introduction, working and different application design, Designing and testing of application using 555, designing and testing circuits using IC 74HC4017 Decade counter, mux, demux, encoder, decoder IC, optoisolator	4	Shivdas S S Nanaware J D					
14-Jun-18	Hands On	Power devices: understanding and working of SCR: SCR BT169 ,TRIAC: Bt138 /bt139/bt151 ,DIAC/SDIAC, Thyristor (SCR or TRIAC): Nxp Bt152-600R 13A or 2N6342A with moc3021 ,Thyristor applications	3	Dr. Kanase Y K					
	Hands On	MOSFET:IRF740,IGBT: Infineon Skw30N60Hs, Different applications using	3	Thorat R A					
16-Jun-18	Hands On	thyristers, mosfets, IGBTs.							
		Switches: Different types of Switches, CMOS Analog Switche, key pads and interfacing OPAMPs: overview, different circuits design using opamps, OPAMPs: study of LM741,	3	Thorat R A					
18-Jun-18		LM358.LM324.TL072.TL082 and other available OPA2604 and OPA2134 Single supply opamp design and dual supply opamp design, Analogue comparator, audio	3	Dr. Godbole B E Shivdas S S					
	Hands On	amplifier, V to I,I to V Signal Conditioning Design and testing, designing of 4-20 ma Current Source, filters and Oscillators design using opamp, Circuit Design: Current, Power Calculation, Heat Sink and	4	Devi R J					
19-Jun-18	Heck- O	Designing a power supply	*	TYCAL IX J					
		Drawing a circuit schematic and Circuit simulation, parameters setting, TINA: circuit simulation using TINA and building the circuit on breadboard and testing of it.	3	Dr. Aldar D S					
20 5 10		PCB Design Process: Layouts, study of aesthetics and convenience, Enclosures	3	Bhandare N D					
20-Jun-18	Hands On	Implementation of schematics, layout and prining using DIPTrace and itching and soldering the components	3	Bhandare N D					
	Hands On	Regulator: Different Regulator Ics, 78XX/79XX/LM317 and applications, TVS: TVS Diode Selection Guide(AND8230), LDO: LP2985 and applications, SMPS LM3524D, Powe supply design and testing, Circuit design using TI Webench, some other utilities for filter design	4	Devi R J Dr. Aldar D S					
21-Jun-18	Hands On	Sensors and Actuators:Temperature Sesnor: LM35,PT100/PT1000/Thermistor/thermocouple,Pressure Sensor: BMP180, Ic based pressure Sensors, proximity sensors,photoelectric sensor,Solenoids, Signal conditioning for sensors and interfacing with ADC	3	Devi R J					
		Embedded C insight	3	Bhandare N D					
22-Jun-18		Microcontrollers:TIVAC123, Arduino	4 -	Bhandare N D & Lokhande S S					
22 1- 10	and the same of the same of	Microcontrollers:TIVAC123, Arduino	3						
23-Jun-18	Hands On	Wired and wireless communication: Bluetooth, Zigbee, RF transmitter receiver, Wifi, Capsense,	4	Dr. Aldar D S					



	Hands On	Linux installation, fundamentals, basic concepts of networking	4	
		Internet Of Things (IOT): ThingSpeak/ Temboo /IBM bluemix demonstation	2 .	Guest Lecture
24-Jan-18		Android App development for Bluetooth and WiFI demonstartion and	1	
		Objective test of 100 marks	2	
		Valedictory function		
	1	Total hrs	113	

Note: All the Staff Memebers are informed to be present throughout the course and carry out the duties assigned by respective faculty members from time to time.

Coordinator

Electronics Engg. Department

Z

Rayat Shikshan Sanstha's
Karmaveer Bhaurao Patil College of Engineering, Satara
Electronics Engineering Department
Certificate course in "Project Based Learning "
ATTENDANCE SHEET



Sr.	Name of Participante	Date:- [4	1901 4	30	Date:-	15/06/118	8	Date:-	18 06 1	2018	Date:-	190161	04
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Rayat Shikshan Sanstha's Karmaveer Bhaurao Patil College of Engineering, Satara Electronics Engineering Department Certificate course in "Project Based Learning" ATTENDANCE SHEET

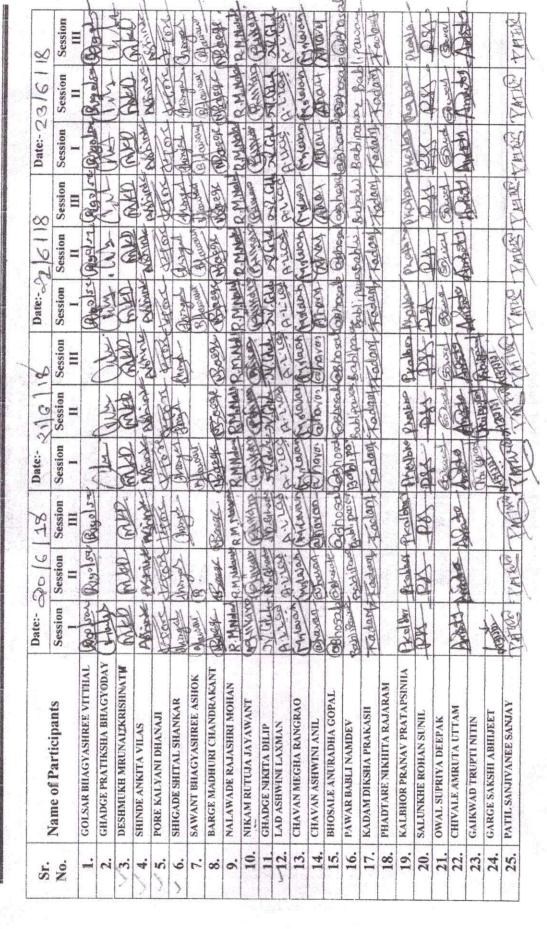
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Rayat Shikshan Sanstha's

Karmaveer Bhaurao Patil College of Engineering, Satara

Electronics Engineering Department

Electronics Engineering Department
Certificate course in "Project Based Learning "
ATTENDANCE SHEET







Rayat Shikshan Sanstha's Karmaveer Bhaurao Patil College of Engineering, Satara Electronics Engineering Department Certificate course in "Project Based Learning" ATTENDANCE SHEET

	Sr. Name of Participants	Date:-	Date: 14 06 18	200	Date:-	15 0	15 06 18	Date:	18/06/18	118	Date:-	Date: 19/06/18	8
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Karmaveer Bhaurao Patil College of Engineering, Satara

Electronics Engineering Department
Certificate course in "Project Based Learning "
ATTENDANCE SHEET

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Sr. 26. 226. 226. 226. 226. 226. 226. 226	f Participants	HAV NIKITA UDAY	ALE MAYURI GORKHNATH	NDE JYOTI BALKRUSHNA			HAV ASMITA PRATAP	WAR RUTUJA NANA	WAR VAISHNAVI MARUTI	SAI SWAPNALI SANTOSH	WALE PRERANA SHAHU	DHAV POOJA VASANT	ARADE PRAJAKTA KASHINATH	AVAN ANJALI SANTAJI	AGE VIJAY DATTATRYA	IT PRAJAKTA DHANANJAY	1	HS			N PRIYA SATISH		10		1	





Rayat Shikshan Sanstha's Karmaveer Bhaurao Patil College of Engineering, Satara Electronics Engineering Department

Certificate course in "Project Based Learning "
ATTENDANCE SHEET

59.	58.	57.	56.	55.	54.	53.	52.	51.	7,1	Sr.
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RAYAT SHIKSHAN SANSTHA'S

KARMAVEER BHAURAO PATIL COLLEGE OF ENGINEERING, SATARA

ELECTRONICS ENGINEERING DEPARTMENT

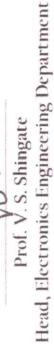
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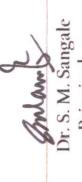
This is to certify that

Mr/Ms/Mrs LAD Ashwini Laxmon

"Project Based Learning" during 5th to 24th June 2018. has completed successfully Certificate course in







Principal

Karmaveer Bhaurao Patil College of Engineering, Satara

Electronics Engineering Department

Test on

Project Based Learning

Ans	swer key	
Q.1] A crystal diode utilises	characteristic for rect	ification
 reverse forward. forward or reverse none of the above Answer: 2 		
Q.2] A zener diode is used as		
 an amplifier a voltage regulator. a rectifier a multivibrator Answer: 2 	្រាប់ល់ដោះ 25 () «	
Q.3] A 10 V power supply would use	daalaallaalla as filter	r capacitor.
 paper capacitor mica capacitor electrolytic capacitor. air capacitor Answer: 3 		
Q.4] A MOSFET can be operated with		
1. negative gate voltage only		

47

2. positive gate voltage only

4. none of the above

Answer: 3

3. positive as well as negative gate voltage.



Karmaveer Bhaurao Patil College of Eng	gineering, Satara
Q.5] For an integrating circuit to be effective, the RC prothe time period of the input wave	roduct should be
 5 times greater than 5 times smaller than Equal to 	
4. At least 10 times greater than. Answer: 4	
 Q.6] An SCR combines the features of	
 Q.7] We can control a.c. power in a load by connecting 1. Two SCRs in series 2. Two SCRs in parallel 3. Two SCRs in parallel opposition. 4. None of the above Answer: 3 	continuates of the country of the co
 Q.8] The purpose of capacitors in a transistor amplifier i 1. Protect the transistor 2. Cool the transistor 3. Couple or bypass a.c. component. 4. Provide biasing Answer: 3 	s to
3. Reduce noise in the amplifier 4. None of the above	
Q.10] If the input capacitor of a transistor amplifier is sh	



Karmaveer Bhaurao Patil College of Engineering, Satara

Department of Electronics Engineering

Student Feedback Form

Academic Year: 2017-18

Date: 24/06/2018

Course Name: Certificate Course in "Project Based Learning"

Students are encouraged to use this form to provide feedback in matters relating to your experience during the course. Your feedback is valuable as it helps us develop and improve our student facilities and services. If you wish to express your opinion towards any aspect of the course, we encourage you to complete the information mentioned below.

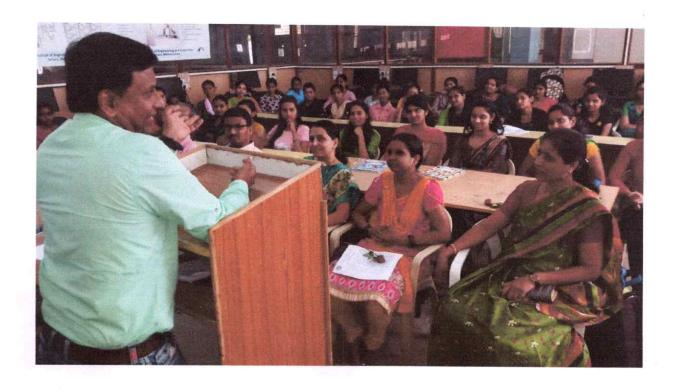
Please Rate as follows:

(Rating: 5-Excellent, 4-Very Good, 3- Good, 2- Average, 1- Below Average)

Sr.	Description				255-25	Names	of Facu	lty			
No	Description	RJD	DSA	JDN	BBG	YKK	SSM	SVM	ANU	NDB	SSL
1	Syllabus coverage of the Faculty as prescribed.	5	5	4	5	9	5	5	9	5	5
2	Effectiveness of the Faculty in terms of Technical content	4	5	4	4	5	4	9	9	4	4
3	Faculty encouragement towards student participation and discussion.	5	5	5	5	5	5	4	5	4	4
4	Use of Non print teaching aids	4	5	5	5	4	4	9	5	4	4
5	Pace on which contents were covered	4	5	5	_5	5	5	5	4	5	5
6	How do you rate the contents of the Course.	4	5	5	5	4	4	5	5	5	9

Any other suggestions:		
	ž	







CERTIFICATE COURSE IN PROJECT BASED LEARNING 5th JUNE TO 24th JUNE 2018





CERTIFICATE COURSE IN PROJECT BASED LEARNING 5th JUNE TO 24th JUNE 2018



Rayat Shikshan Sanstha's Karmaveer Bhaurao Patil College of Engineering, atara

Mechanical Engineering Department Academic Year (2018-2019) Project Based Learning Ativity

Class: B.E. Mechanical

Course Code:

Program Code:

Course: Mechatronics

Course Coordinator: Prof. Ms.shivdas R.K

	T				T				T			-		T		_	******	Т	_		
Components Used	Transistor: BC548	• Resistor: 3300hm	• LED: Red, Green, Yellow	Euzzel - Battery: 9V Zero PCB (Printed Circuit Board)			• Capacitor: 10uf, 0.01uf • LED	Battery: 9V Zero PCB (Printed Circuit Board)	• IR sensor module	• Battery, 9V				• DC geared motor	DPDT (Double Pole Double Throw)	Switch	- Datterly, 9V	• Transistor: BC547	• Resistor: 470 ohm	·LED	• Battery: 9V • Zero PCB (Printed Circuit Board)
Outcome	To make circuit for water level developed the water level indicator	(Gauge) using. • Transistor: BC548	• Resistor: 330ohm	* Buzzer	The IC 555 timer is used to determine	the time of the 2 LED stays ON &	OFF		Made circuit proving application of IR • IR sensor module	sensor				DC motor controlled in clockwise or	F	(Double Pole Double Throw) Switch.		The touch sensor circuit is built with	touch sensor by making circuit three components such as a resistor, a	transistor and a light emitting diode.	
Objective	To make circuit for water level	indicator			To use IC 555 Timer in	mechtronics circit			9	prove its working principle				switch in	electric circuit			To demonstrate application of	ouch sensor by making circuit		
Roll No. Fabricated Mechatronics Simple Project	Water Level Indicator			×	2 LED flashers				dule (sensor	application):				DPDT switch application				Touch Sensor			= 1
Roll No.				i.		0															
Name of the Student	Nitiraj More	AkashSawant	KiranJangam	SwapnilKarande	RavirajBaswant	GirishJagtap	Rajesh Shirke		Omkar Patil	GhadageDhiraj	SirsatVikas	PankajKalbhor	Jadhav Ganesh(P)	WaghRohit A	YadavDhanaji S	Barge Mayur	KajleAkshay	MullaSahilRajjak	TarangeMadhav	KambleShrikant	Lad ShivamShankarrao
Gr. No.	1				7.				3.			S.T		4.				5	article Con-		

	Dain Akuvaku LED	To prove working of LDR	Devloped circuit that proves working	• Transistor: BC547
Amar Kumbhar			of Light Dependent Resistors (LDR)	• Resistor: 3300hm, 100kohm • I DR (Lioht Denendent Besistore)
OmkarRaut				• LED
Omkar Pol				• Battery: 9V
OmkarShinde	LED Chaser	To use IC 555 Timer in	Developed LED Chaser circuit using	• IC 555 (Timer IC)
PranavPawar		mechtronics circit	IC 555 (Timer IC)	• 4017 (Decade Counter IC)
AmeyKulkarni				• Resistor: 470ohm, 10kohm
HarshalMalawade	0			· Capacitor: 10uf
		Alogo 12		Battery: 9V Zero PCB (Printed Circuit Board)
SurajKadam	. Water Level Controller	To use IC 555 Timer in	Developed Water level controller	• IC 555 (Timer IC)
OmkarKaranjkar		mechtronics circit	circuit using IC 555 (Timer IC)	Transistor: BC548 Resistor: 1000hm 10kohm
Prasad Mangarule				• Diode: 1N4007
Akshay Patil				• Relay: 12V • Adapter: 12V, 2A • Zero PCB (Printed Circuit Board)
Akshay Kale	DPDT switch application	To use DPDT switch in	DC motor controlled in clockwise or	• DC geared motor
AkshayPilaware		electric circuit	anti-clockwise direction using a DPD L (Double Pole Double Throw) Switch	• DPD1 (Double Pole Double Ihrow)
Parthyi Patil			Control Control Control	• Battery: 9V
Dhananjay D.				
Sahil Patel(P)				
ShivanjaliDhadame	ne IR Sensor with Output	To apply IR sensor in circuit	Devloped circuit that proves working	• IR sensor module
Sarswatikore	7		of IR LED (Light Emitting Diode) and • IC 7805: Voltage Regulator 5V	I • IC 7805: Voltage Regulator 5V
AbhayaGaikwad		a	the detector IR photodiode	• Resistor: 330ohm
ShivaniChavan				· Battery 9V
Ajay Nikam	Limit switch with DC	To apply Limit switches in	Made Circuit using Limit switch with	
MuaajChawadiwale	ale motor	control circuit	DC motor	• DC geared motor
SanketPanaskar				Battery: 9V
Shahabaz Bagwan		To use PIR sensor for motion	Made circuit using PIR sensor that	• PIR (Passive InfraRed) sensor module
Suhel Bagwan	detection)	detection	detects any change in motion	• Resistor: 470ohm
Jagtap Pratik		81		• Battery: 9V
Vinode Madure				Zero PCB (Printed Circuit Board)
Prathamesh Bhange	99			

13.	SnehalDeshmukh	Water Level Indicator	To develop water level	developed the water level indicator	Transistor: BC548
	PoojaKarande		indicator circuit	(Gauge) using. • Transistor: BC548	• Resistor: 330ohm
	VidyaPawar			• Resistor: 330ohm	• LED: Red, Green, Yellow
	SapanaSawant			• LED: Red, Green, Yellow • Buzzer	 Buzzer* Battery: 9V Zero PCB (Printed Circuit Board)
14.	SohailInamdar	. Soil Moisture Tester	To make Soil moisture tester	Working Circuit of soil moisture tester • Transistor: BC547	• Transistor: BC547
	SahilShinde			is developed	• Resistor: 330ohm
	Abhishek Jadhav				• Buzzer
	PranavMohite				 Zero PCB (Printed Circuit Board)
15.	SanyuktaBhosale	Single LED flasher	To use IC 555 Timer in	The IC 555 timer is used to determine	• IC555 (Timer IC)
	KomalKamble		mechtronics circuit	the time of the LED stays ON & OFF	• Resistor: 330ohm, 10kohm, 1kohm
	PrajktaKenjale				Battery: 9V
	MrunalBhondave				·LED
16.	ChavanPareshGanpa	Limit Switch application	To apply Limit switches in	Made Circuit with limitswitch	Limit switch
7. 91	GadiwaddarGopal		control circuit	controoling D.C Motor	• DC geared motor
	RathodSwapnilRam				- Dallely, 9V
	PawarSagarPrakash				
17.	KadamChandanRaje	PIR sensor (Motion	To use PIR sensor for motion	Made circuit using PIR sensor that	• PIR (Passive InfraRed) sensor module
	DhayugadeTejaswiD	detection)	detection	detects any change in motion	• Resistor: 470ohm • I ED
	Barge				• Battery: 9V
	ShubhamRajendra	1			 Zero PCB (Printed Circuit Board)
	MahannuniOmkar				
18.	Jadhav Vikas P.	Light Activated LED	To Use light activated LED in	To Use light activated LED in Made Circuit using light activated	Transistor: BC547
	SayyedJaid H.		Circuit	TED	• Resistor: 3300hm, 100kohm
	Chavan Akash D.				• LDR (Light Dependent Resistor) • LED
					• Battery: 9V
					 Zero PCB (Printed Circuit Board)
19.	Avinash Mane				
	Shraddha Chavan				

Mechanical Engineering Department K.B.P Coilege of Engineering, Satara

Course coordinator



Karmaveer Bhaurao Patil College of Engineering, Satara

Academic Year: 2018-19 Semester-II

Name of the Program: Electronics Engineering Program Code: 627004
Name of the Course: Elective II(HPCN) Course Code: EL410

Class: B.E.

Roll No.	Sr.No.	NAME OF STUDENT	Topic	Sign.
Elect/BE/2018/5	2	CHAVAN MEGHA R.	Configuration	(prolaton
Elect/BE/2018/6	3	CHAVAN ASHWINI A.	of Switch for	Thors
Elect/BE/2018/34	4	KADAM DIKSHA P.	Gigabit Ethernet	Kodany
Elect/BE/2018/3	5.	CHAVAN ANJALI S.	Interfaces	Adjavon
Elect/BE/2018/9	6	DESAI SWAPNALI S.		MPTOCY
Elect/BE/2018/47	7	NALAWADE RAJASHRI M.		R.M. Noland
Elect/BE/2018/49	8	NIKAM RUTUJA J.	. (PHIXAP
Elect/BE/2018/16	9	DIXIT SNEHAL ANIL		MOIXIL
Elect/BE/2018/26	10	GUJAR SAPNA B.		632
Elect/BE/2018/25	11	GORE NAMRATA S.		NSCOR
Elect/BE/2018/41	12	LAD ASHWINI L.		AT-Tag
Elect/BE/2018/1	13	BARGE MADHURI C.		Barge
Elect/BE/2018/4	14	CHAVAN MAYURI S.		Medous
Elect/BE/2018/43	15	LOKHANDE POOJA D.		
Elect/BE/2018/38	16	KHAJURE DHANASHREE T.		Thajese
Elect/BE/2018/12	17	DHAGE VIJAY D.		Gards
Elect/BE/2018/20	18	GARGE SAKSHI A.		(13H3H3)
Elect/BE/2018/50	19	OWAL SUPRIYA D.		
Elect/BE/2018/7	20	CHIVALE AMRUTA U.		America
Elect/BE/2018/18	21	GAIKWAD TRUPTI N.	Design of	Pailcood
Elect/BE/2018/36	22	KALBHOR PRANAV P.	Computer Network of 10	PROUBLO
Elect/BE/2018/62	23	SALUNKHE ROHAN S.	Computers and	PSS:
Elect/BE/2018/14	24	DISALE MAYURI G.	Router	W/sale
Elect/BE/2018/21	25	GHADGE PRATIKSHA B.	Configuration	Thadexe
Elect/BE/2018/28	26	JADHAV NIKITA U.		literally
Elect/BE/2018/53	27	PATIL SANJIVANEE S.	<	MISON
Elect/BE/2018/40	28	KOLEKAR MINAL H.		Dalet.
Elect/BE/2018/65	29	SAWANT BHAGYASHREE A.		Stawaur_
Elect/BE/2018/60	30	PHADTARE NIKITA R		3 Phack
Elect/BE/2018/44	31	MALAVE AMRUTA A.		DOS.
Elect/BE/2018/61	32	PORE KALYANI D.		ETOR
Elect/BE/2018/66	33	SHINDE POOJA P.		1200/92
Elect/BE/2018/69	34	SHINGADE SHITAL S.		Thursday
Elect/BE/2018/10	35	DESHMUKH PRATIK S.	Configuration	Shmut
Elect/BE/2018/27	36	INGAWALE PRIYANKA A.	of Router	P.P Depute
Elect/BE/2018/84	37	KAZI ARBAZ C.		· AMDI
Elect/BE/2018/87	38	MORE ANKITA R.		

Elect/BE/2018/24	39	GOLSAR BHAGYASHREE V.		(Pgolsa,
Elect/BE/2018/39	40	KHARADE PRAJAKTA K.		Phonads
Elect/BE/2018/32	41	JAIN PRIYA SATISH		Josh-
Elect/BE/2018/90	42	PHADATARE ANIKET A.		etholdators
Elect/BE/2018/11	43	DESHMUKH MRUNAL K.		WED
Elect/BE/2018/30	44	JADHAV POOJA V.	Configuration	Jarthou
Elect/BE/2018/68	45	SHINDE ANKITA V.	of Router	Albert
Elect/BE/2018/51	46	PARMANE SUPRIYA		SPRE
Elect/BE/2018/15	47	DIXIT PRAJAKTA D.		Ord.
Elect/BE/2018/22	48	GHADGE NIKITA D.		W. Styr
Elect/BE/2018/54	49	PAWAR VAISHNAVI M.		Made
Elect/BE/2018/33	50	JAWALE PRERANA S.		Pauale
Elect/BE/2018/64	51	SAWANT PRAJAKTA D.		From.
Elect/BE/2018/63	53	SAWANT AMRUTA M.		Againt.
Elect/BE/2018/2	54	CHALKE RIDDHI D.	Design of	light.
Elect/BE/2018/58	55	PHADTARE MADHURI	Computer Network of 15	Produku
Elect/BE/2018/29	56	JADHAV ASMITA P.	Computers	Dicolo?
Elect/BE/2018/67	57	SHINDE JYOTI B.	Property of	Hinds
Elect/BE/2018/46	58	MANE ASHWINI G.		CARUM
Elect/BE/2018/55	59	PAWAR BABLI N.		Pabli Paur
Elect/BE/2018/56	60	PAWAR RITUJA N.		
Elect/BE/2018/17	62	DOLAS SWATI G.		2010
Elect/BE/2018/19	64	GAIKWAD RAJESH S.		
Elect/BE/2018/94	68	YADAV NIKITA S.		Hada,
Elect/BE/2018/80	69	KADAM ASHUTOSH		1513
Elect/BE/2018/86	71	LOHAR RAVINA J.		(delive
Elect/BE/2018/45	73	MANE SHRIKANT A.		
Elect/BE/2018/71	74	UMBARDAND S. G.		Shiel.
Elect/BE/2018/78	76	GHODAKE SAISH G.		
Elect/BE/2018/13	77	DHANE AKSHAY R.		lun
Elect/BE/2018/70	78	SURYAWANSHI AVINASH S.		
Elect/BE/2018/59	79	PHADTARE PRASAD T.	Speed	
Elect/BE/2018/52	81	PASALEKAR VINAYAK S.	improvement of LAN	@inavas
Elect/BE/2018/48	82	NAWADKAR SHANTANU S.		
Elect/BE/2018/42	83	LOKHANDE SUMIT R.		Smil
Elect/BE/2018/37	84	KAMBALE ANIKET S.		Reser
Elect/BE/2018/72	85	YEWALE NIPUN U.		10
Elect/BE/2018/57	86	PAWAR AJIT V.		BU
Elect/BE/2018/31	87	JADHAV AVINASH D.		(A) Jack
Elect/BE/2018/23	88	GHATGE KULDEEP		
Elect/BE/2018/35	91	KADI KETAKI		

Subject Incharge 1- Mrs. Ulmek A.N.



Rayat Shikshan Sanstha's Karmaveer Bhaurao Patil College of Engineering, Satara

Project Based Learning

Program with code: Production Enga [62706]
Class: TE
Semester: <u>VI</u>
Academic Year: 2018-19
Course with code: Industrial Hydraulic (Preumatics [PE 309]
Project title: Design and development of Hydraulic
Press with die



Karmaveer Bhaurao Patil College of Engineering, Satara

Group Members:

Roll No	Name
6	Abhmanya B Dhane
12	Aniket N. Kanse
13	Dinesh V. Kathar.
14	Akshay N kavade.
72	Aakash M. Pawar

Faculty Name and Designation Astrof Mr. A.M. Shakh.

Objectives: Hydraulic press is a tool to procluce

Compressive Force by means of fluid. -1 J's

depends upon Pascal's principles that that

Thoughout an endosed entity is constant.

Outcome: Thus the whole mechanism have been simplified with use of hydraulic equipments. Moreover, the use of pressure control value and direction control value the forces and Control speed of the setup.

Materials/Tools/Components/Equipments Used: Ram, Punch,

Die, Bed, Bolster, support stauture.



Karmaveer Bhaurao Patil College of Engineering, Satara

Schedule:

Duration	Activity	Remark
1-2 hour	Collect the information	Remark
30min	Ser the hydraulic circuit	
15 min.	selection of DCV as per operation	

Theory/Design/Methodology: The operation sequence of	h€.
designed hydraulic press. A	sone
ian observe from the diagram that the moveme	ent of
the cylinder is being regulated by means of lever whi	ch
designed hydraulic press. A ian observe from the diagram that the movement is being regulated by means of lever whis indicate atomized later.	
Results Discussion: The speed of blanking operation	
is accordedly controlled by flow control value	e.
Conclusion: This may increase the productivity and	
press can be completerly automize by wring the concept of cet rehydraulics. Direction value of be solenoid actualed to make the system (10:	he
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concept of cetrohydraulics. Direction value o	an
be solenoid actualed to make the system (10)	ے ح
100 p.	

References



Karmaveer Bhaurao Patil College of Engineering, Satara

[1]. Design Edevelopment of Hydraulia press Die 5th National
[2]. conference on Recent Advance on Manufactum og
[3]. (Ram-2015) 15 17 may-2015

1.0 INTRODUCTION

Hydraulic press is a tool to produce compressive force by means of fluid. It depends upon Pascal's principle that the pressure throughout an enclosed entity is constant. By means of hydraulic system larger forces can be produced in contrast with mechanical and electrical systems. Such forces can be used for the press work application such as blanking, punching, piercing, coining, trimming etcetera.

Press work is a method of mass production involving the cold working of metals, usually in the form of thin sheet or strip. Press working is one of the extensively employed methods of fabricating parts of intricate shapes with thin walls. Press working processes make use of large forces by press tools for a short time interval which results in cutting or shaping the sheet metal. Since, press working does not involve heating of the parts, close tolerances and high surface finish can be obtained on the part. Since presses can produce components at fairly fast rates, the unit cost of labour for operating the press is fairly low.

Press working forces are set up, guided and controlled in a machine referred to as a Press. Thus an attempt has been made to atomize the process of press work using Hydraulic mechanism in press machine. The inputs and outputs of the control system including hydraulic mechanism are solely mechanical such as rotating shaft or reciprocating plunger. The prime remuneration of implementing this system is the movement of the mechanical devices can be operated by means of hydraulic components such as actuators to initiate the movement which could be in the form of lever to apply manually or by means of switches to operate automatically. Furthermore, direction control valves have been implemented to control the directions of piston movements and regulate the same. Thus the whole mechanism have been simplified with the use of hydraulic equipment. Moreover, the use of pressure control valve and direction control valves, makes it easier to regulate the forces and control the speed of the setup.

2.0 Design and modelling of the parts for proposed set up

The proposed set up is shown in figure 1 below, gives the brief of required components to be assembled together.

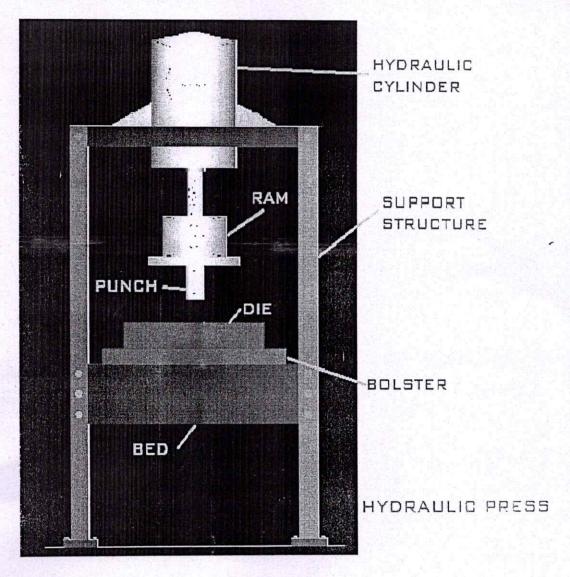


Fig. 1 The Proposed Set Up Of Hydraulic Press

2.1 Support structure

It is an assembly of support frame and bed. Both the channels bolster each other with the help of a supportive plate welded at the top of the structure. Further it is welded at the foundation to give the whole assembly a framed structure. The bed which holds a die is clamped on the holes.

2.2 Bed

Bed is a plate on which the die is supposed to hold. It is used for mounting the die on support frame at desired position. Figure 3 shows the design of bed where the holes produced on the sides shows the support plate to be clamped on support frame.

2.3 Die

Die is an integral part of any manufacturing process which enables the desired shape that one require. Here for the experimental purpose a compound die have been used which produces a washer from the strip of sheet metal. The dimensions of the outcome washers are as follow. Outer diameter = 30 mm, Inner diameter = 10 mm. A blanking die produces a flat piece of material by cutting the desired shape in single operation.

2.4 Punch

Punch is the male component of die. In compound die we used two punch one cuts inner diameter of washer and another cuts outer diameter of same. Punch which cuts I.D. is placed at bottom side of female die. Second punch that cuts outer diameter of washer is attached with piston rod of hydraulic cylinder. Position of same punch is above side of die. Here figure 6 shows the section view of punch that cuts outer diameter.

2.5 Plunger and Hydraulic cylinder

Plunger has been purchased from the market. Main function of plunger in our project is it provides required hydraulic pressure to our hydraulic cylinder. Hydraulic cylinders get their power from pressurized hydraulic fluid, which is typically oil. The hydraulic cylinder consists of a cylinder barrel, in which a piston connected to a piston rod moves back and forth. The barrel is closed on each end by the cylinder bottom (also called the cap end) and by the cylinder head where the piston rod comes out of the cylinder. The piston has sliding rings and seals. The piston divides the inside of the cylinder in two chambers, the bottom chamber (cap end) and the piston rod side chamber (rod end).

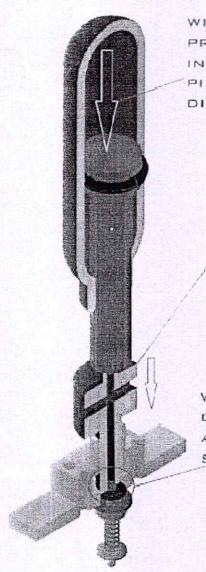
3.0 WORKING OF SET UP

Hydraulic press is used in mass production. Working cycle of hydraulic press is very quick so production increases.

In hydraulic press hydraulic energy first converted in to kinetic energy of piston. This kinetic energy produces shear stress between die and punch which cuts the metal. Description of working of hydraulic press is started from plunger. It's based on Pascal's law, which states that the intensity of pressure in a static fluid is transmitted equally in all direction. Here plunger and cylinder connected with pipe to each other.

Here when we increases the pressure of fluid in plunger then according to Pascal's law intensity of pressure in static fluid is transmitted from plunger to cylinder thru pipe which connected cylinder and plunger.

In cylinder as the intensity of pressure in fluid increases it push the piston outside cylinder. Because of this punch which is attached at one end of piston also moves in direction of piston.



WHEN INTENSITY OF
PRESSURE IN FLUID
INCREASES IT PUSH THE
PISTON IN MONTIONED
DIRECTION

WHEN THE PISTON
MOVES IN DOWNWARD
DIRECTION PUNCH
ALSO MOVES IN SAME
DIRECTION

WHEN PUNCH MOVES
DOWN THEN PUNCH & DIE
ACROSS EACH OTHER AND
SHEAR STRESS INDUSED

Fig.2Concept OI Working OI Press

As the punch moves downward direction it across the die thru a guide way. If metal strip placed between die and punch then when the punch across the die then shear stress induced between die and punch.

Because of this shear stress metal strip cut in shape of die and final product is produce.

Here O.D. of washer cuts from outer edge of upper punch and die. And I.D. of washer cuts from outer edge of lower punch and inner edge of upper punch.

5.0 INTEGRATING THE SETUP WITH HYDRAULIC CONTROL SYSTEM

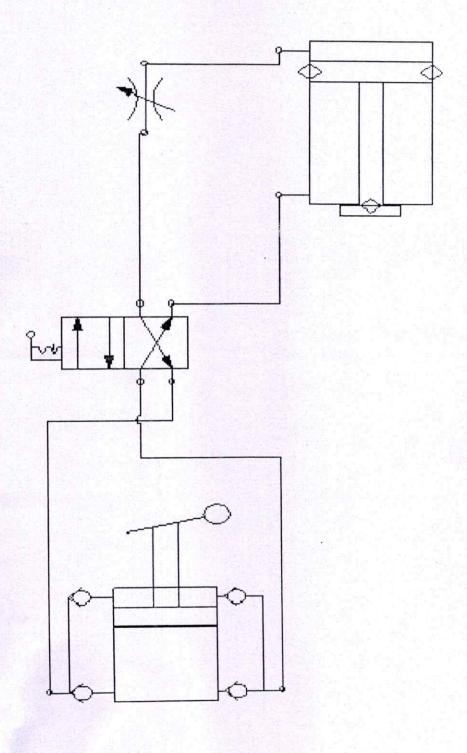


Fig. 3 Hydraulic circuit of the experimental apparatus

6.0 CONCLUSION AND FUTURE SCOPE

Thus here a hydraulic system is used to develop a press. The press will be useful for mass production of Washers. This may increase the productivity and increases the accuracy of the production. Even the press can be complete rely automize by using the concept of ectrohydraulics. Direction control valve can be solenoid actuated to make the system close loop. Which may lead to higher production rate.



Rayat Shikshan Sanstha's Karmaveer Bhaurao Patil College of Engineering, Satara

Project Based Learning

	s: B. E
	ester: VIII
Aca	demic Year: 2018-19
Cou	rse with code: Mechatronics



Karmaveer Bhaurao Patil College of Engineering, Satara

Group Members:

Roll No	Name
01.	Bogwan. Stahalaz.S Bogwan. Suhel. H
02.	Bogwan. Suhel. H
24.	Jaglap. Prakk, VS.
42	Madure. Vinod, V

Faculty Name and Designation:	Prof. Ms.	Shirdas . R. k	

Objec		_311				
;)	To we	PIR	500 500	for m	oten de	etection.
(1)	To an	et kno	wledge of sensor)	about a	pplication	700
100	PIR	motion	sensor)	Driet in	t Dring.	LUNCTURE
En			detail			
)		Cooce		EXPERIMENT		

Outcome: i) made circult wing PIR sensor that

Materials /Tools/Components /Equipments Used:___

- · PIR Passive Infra red sensor module
- · Resistor: 470 ohm

- · LEDO:- Red, Green, religio · Buzzer:- Battery: 90 · Zero PCB: (PCB (Printed Circuit Board)



Rayat Shikshan Sanstha's Rayat Shikshan Sanstha's

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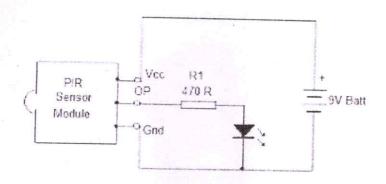
Schedule:

Duration	Activity	Remark
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To	PIR sensol in motion detection	Completed
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	traking model of motion detection	Lagrand Fak
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	2 rehard - M kard maissashed has	Faculty Name

Theory/Design/Methodology:	
- Paysive Infrared (PIR) sens or module	is very
tracket made to haild many to	and of
security alarm systems and notion beter	ton. It is
carled partire because it receives in how	ed, not emists
security alarm systems and motion beter cased passive because it receives in from They are also referred by IR motion senson Results Discussion:	1.
- PIR sensor defects any change in whenever it defects any change, its out	
wherever it detects any change its out	put PIN beron
HIGH TOWN TO STOKE WE TO THE TOWN THE T	24.45
- Our group disrused on the application	y of PIRSE
Conclusion:	
- We concluded from this short of	nechabonic
project on PIR motion sensor. - We learn't from this that PI	2 50000
can be wed in security alarm sys	tem.
u offst more	
References	ru: 'Si
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Expriment No.5

Fabrication of Simple Mechatronics Project PIR sensor (Motion Detection):



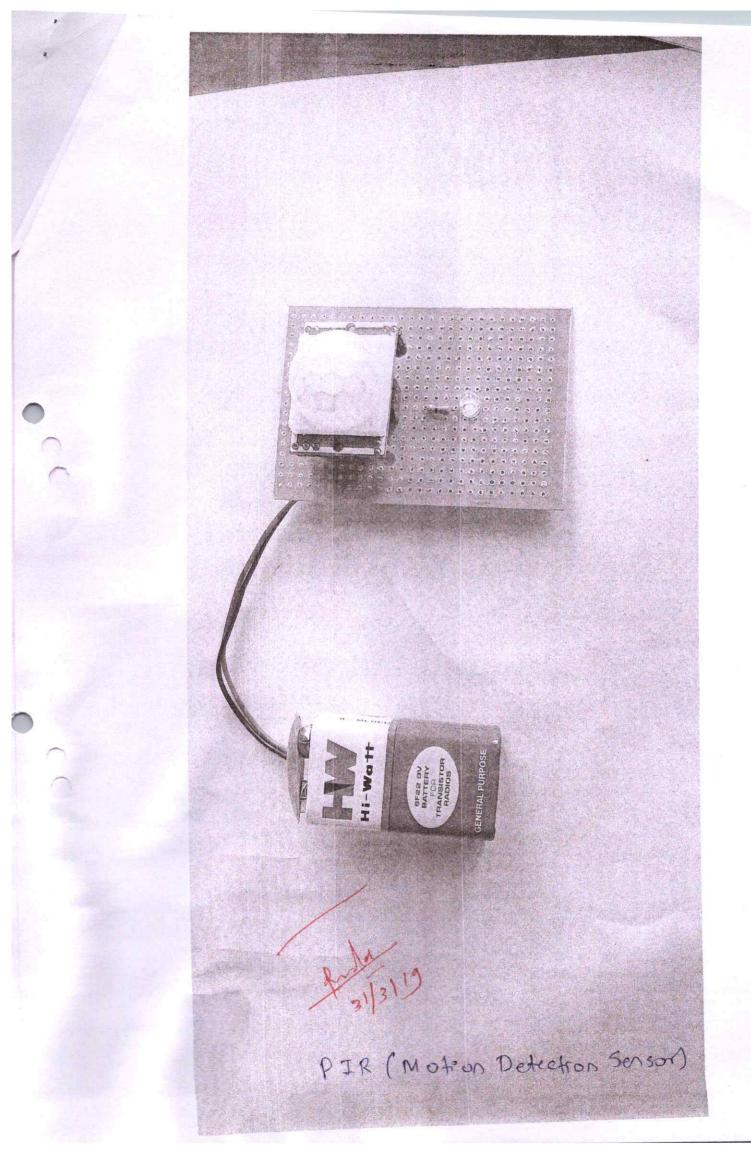
Components:

- PIR (Passive InfraRed) sensor module
- · Resistor: 470ohm
- LED
- Battery: 9V
- Zero PCB (Printed Circuit Board)

Working:

Passive Infrared Sensor (PIR) is very useful module, used to build many kinds of Security Alarm Systems and Motion Detectors. It is called passive because it receives infrared, not emits. Basically PIR sensor detects any change in heat, and whenever it detects any change, its output PIN becomes HIGH. They are also referred as IR motion sensors.

Group Members: 1) Bag wan, Shahabaz. S 27 Bag wan, Suhel. H 3) Jagtap. Pratik. S 4) Madure Vinod. V.



		8	ook Bank	Book Bank Issue /Return Details 2018-19	Details 2	018-19			
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4	BE Civil	21	90	3	6	22	59	3	6
2	BE computer	18	9	5	16	12	32	2	9
9	TE Electronic	26	81	5	17	24	89	4	16
7	TE Computer	42	173	5	23	44	139	5	17
∞	TE Production	16	74	2	9	11	41	0	0
6	TE Mechanical	11	38	6	25	15	54	7	21
10	TE civil	15	33	3	6	6	29	2	9
11	SE computer	18	52	2	9	16	40	2	5
12	SE Mechanical	34	115	3	5	22	50	3	6
13	SE Civil	17	68	4	16	2	9	3	∞
14	SE Electronics	27	82	2	9	11	26	4	12
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BOOK-BANK NOTICE 2018-19 SEMESTER - I

Date :- 18/07/20118

All the students are hereby informed that those who are interested to take books under Book-Bank Scheme, should remain present to get books under Book-Bank scheme as per following schedule. The Book-Bank forms should submit in the library on or before 21/07/2018.

All the scholarship holder students of SC & ST categories can get the books free of Cost, should attach attested Xerox copies of their caste certificate and Annual Income Certificate (Less than Rs.2,00,000) with Book-Bank form.

IMP Note-: Please make online payment only.

Link-: www.kbpcoes.edu.in or www.onlinesbi.co.in

	DATE	TIME	CLASS
		10.00 to 12.00	BE Mechanical
Tuesday	24.07.2018	12.00 to 02.00	BE Production
		03.00 to 05.00	BE Electronics
		10.00 to 12.00	BE Civil
Wednesday	25/07/2018	12.00 to 02.00	BE Computer
		8 12.00 to 02.00 03.00 to 05.00 10.00 to 12.00 8 12.00 to 02.00 03.00 to 05.00 10.00 to 12.00 8 12.00 to 02.00 03.00 to 05.00 10.00 to 12.00	T.E.Electronics
		10.00 to 12.00	TE Computer
Thursday	26/07/2018	12.00 to 02.00	TE Production
		03.00 to 05.00	TE Mechanical
		10.00 to 12.00	TE Civil
Friday,	27/07/2018	12.00 to 02.00	S.E.Computer
		03.00 to 05.00	S.E.Mechanical
Saturday	28/07/2018	10.00 to 12.00	S.E.Civil
	20/0//2010	03.00 to 05.00	S.E.Electronics

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Copy to:- HOD's (Civil, Prod., Mech., Elect., Comp., Gen., Office & Library Notice Board)

Note :- 1) Library Registration is Compulsory.

- 2) Book- Bank forms are available in Xerox Centre.
- 3) Book- Bank Deposit receipt, Admission Fee Receipt (2018-19) & I-Card should be produced while taking the books.

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BOOK- BANK NOTICE For F.Y.B.Tech 2018-19 SEMESTER - I

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DATE	TIME	CLASS
Ditta	10.30 AM	F.Y.Mechanical
	12.30 PM	F.Y.Computer
21/08/2018	03.00 PM	F.Y.Civil
	05.00 PM	F.Y.Electronics

Karmaveer Bhaurao Patil College of Engineering , Satara.

Copy to :- HOD Basic Sciences & Humanities, (Office & Library Notice Board)

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- 3) College Admission Fee Receipt (2018-19).
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Date :- 04/01/2019

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	DATE	TIME	CLASS
		10.00 to 12.00	BE Civil
Monday	14/01/2019	12.00 to 02.00	BE Computer
3		03.00 to 05.00	BE Electronics
		10.00 to 12.00	BE Mechanica
Tuesday	15/01/2019	12.00 to 02.00	BE Production
		03.00 to 05.00	T.E.Civil
		10.00 to 12.00	TE Mechanica
Wednesday	16/01/2019	12.00 to 02.00	TE Production
		12.00 to 02.00 03.00 to 05.00 10.00 to 12.00 12.00 to 02.00 03.00 to 05.00 10.00 to 12.00	TE Computer
		10.00 to 12.00	TE Electronics
Thursday	17/01/2019	12.00 to 02.00	S.Y.Electronics
		03.00 to 05.00	S.Y.Civil
		10.00 to 12.00	S.Y.Mechanica
Friday	18/01/2019	12.00 to 2.00	S.Y.Computer
		03.00 to 5.00	F.Y. Electronic
		10.00 to 12.00	F.Y.Mechanica
Saturday	19/01/2019	12.00 to 2.00	F.Y.Computer
14 december 2 x 1000 5 x 1000 € 27		03.00 to 5.00	F.Y. Civil

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	3	Building Construction	Bindrea Avora
150	4	Engg. & Geo	Probin Singh
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Sr. No.	Name of the Book	Author
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2	surveying and develling	Basak
3	Theory of istructures	Ris khurmi
4	strength of materials	31 Ramamoutham
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			Student's Signature अन्तर्गाप
For Office use (only.	:	
	he Sanctioned books		
Paid Rs	Vide receipt No		

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RAYAT SHIKAHAN SANSTHA'S KARMAVEER BHAURAO PATIL COLLEGE OF ENGINEERING,SATARA. BOOK-BANK FORM Year- 2018- 19 SEMESTER I / H

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